

DAFTAR PUSTAKA

- [1] Anton, H. 1991. *Aljabar Linier Elementer Edisi Kedelapan-Jilid 1*. Erlangga. Jakarta.
- [2] Beauthier, C. dan Joseph J. Winkin. 2010. *LQ-Optimal Control of Positive Linear System*. Wiley Online Library.
- [3] D.G. Luenberger. 1979. *Introduction to Dynamic Systems*. Wiley. New York.
- [4] Farina, L. dan Rinaldi, S. 2000. *Positive Linear Systems : Theory and Applications*. Wiley. New York.
- [5] Hendricks. Elbert, Ole. Jannerup dan P. H. Sorensen. 2008. *Linear Systems Control*. Springer- Verlag Berlin Heidelberg.
- [6] Kaczorek, T. 2001. *Positive 1D and 2D Systems Metzler Matrices*. Springer-Verlag Berlin Heidelberg.
- [7] Leenheer, P. dan D. Aeyels. 2001. *Stabilization of Positive Linear Systems*. Systems and Control Letters. **44**: 259-271.
- [8] Meyer. Carl D. 2000. *Matrix Analysis and Applied Linear Algebra*. SIAM.
- [9] Naidu, D.S. 2002. *Optimal Control Systems*. CRC Press, Idaho.
- [10] Mitkowski. W. 2008. *Dynamical Properties of Metzler Systems*. Bulletin of The Polish Academy of Sciences Technical Sciences. Vol. 56, No. 4.
- [11] Richard, Charles Jhonson. 1982. *Inverse M-Matrices*. Algebra Linier and Its Applications 47:195-216.

- [12] Roszak, B. dan Davidson, E. J. 2014. *Optimal Complementary Control for Positive Stable LTI Systems*. Automatica 50(2014) 1401-1406.
- [13] Roszak, B. dan Davidson, E. J. 2009. *Necessary and Sufficient Conditions for Stabilizability of Positive LTI System*. System and Control Letters 58(2009). 474-481.

