

DAFTAR KEPUSTAKAAN

- [1] Dhudhik Arief H. Rizky Wahyu K. Yusi Kusuma A. 2015. *Lengan Robot Pemindah Barang lengan Pengendali Joystick*. Politeknik Negeri Semarang. Semarang.
- [2] Syafrudin, Muhammad. Fitri, Nyayu. 2012. *Perancangan Sistem Kendali Gerak Lengan Robot Pengikut Gerak Lengan Manusia Berbasis Mikrokontroller*. STMIK GI MDP, Palembang.
- [3] medical-dictionary.thefreedictionary.com. 2009. *Electrooculogram*. <http://medical-dictionary.thefreedictionary.com/electrooculogram>. Diakses 3 Maret 2017 jam 09.39 WIB.
- [4] Rusydi, M. I. Sasaki, M. Ito, S. dkk. 2015. *Robot Control System Based on Electrooculography and Electromyography*. Gifu University. Japan.
- [5] Rusydi, M. I. Sasaki, M. Ito, S. 2014. *Affine Transform to Reform Pixel Coordinates of EOG Signals for Controlling Robot Manipulators Using Gaze Motions*. Gifu University. Japan.
- [6] Lanez, Eduardo, Hernandez, Miguel. 2012. *Assistive robot application based on an RFID control architecture and a wireless EOG interface*. University of Elche, Spain.
- [7] Tsai Sung, Wen. 2012. *ZigBee based multi-purpose electronic score design and implementation using EOG*. University of Technology, Taiwan.

- [8] Khan, Abdullah. Awais, Muhammad. Jat, Yusra. Khan, Ali. 2012. *Electrooculogram Based Interactive Robotic Arm Interface for Partially Paralytic Patients*, Mehran UET, Jamshoro Pakistan.
- [9] Sasaki, Minoru. Syaiful, Muhammad. Matsushita, Kojiro dkk. 2015. *Robot Control System Based on Electrooculography and Electromyogram*. Universitas Gifu, Jepang.
- [10] W. Heide, E. Koenigb, P. Trillenberga, D. Ko Èmpfa and D.S.1999. *ZeecElectrooculography: technical standards and applications', Guidelines of the International Federation of Clinical Physiology (EEG Suppl. 52)*.
- [11] Tanpa Nama, Tanpa Tahun, Ambu Blue Sensor,
http://www.ambu.com/corp/products/patient_monitoring_and_diagnostics.aspx.
 Diakses 26 Maret 2017 Pukul 21.21 WIB.
- [12] Syam, Rafiuddin, 2015. Kinematika Dinamika Robot Lengan. Makassar. Universitas Hasanuddin.
- [13] Tanpa Nama. 2016. *Robot Arm*.
http://wiki.sainsmart.com/index.php/DIY_6Axis_Servos_Control_Palletizing_Robot_Arm_Model_for_Arduino_UNO_MEGA2560. Diakses pada 24 Maret 2017 Pukul 21.00 WIB
- [14] Tanpa Nama. Tanpa Tahun. *NI Product Manuals*. <http://www.ni.com/manuals/>.
 Diakses 26 Maret 2017 Pukul 22.00 WIB.

- [15] Arduino. 2016. *Arduino UNO*. [http://arduino.cc/forum.\[Online\].](http://arduino.cc/forum.[Online].)
<https://www.arduino.cc/en/main/arduinoBoardUno>. Diakses tanggal 27 Maret 2017 Jam 06.50 WIB.
- [16] Parwitasari, Nila. 2013. *Motor Servo Pada Robot*. Jakarta. Sekolah Tinggi Teknik -PLN.
- [17] Tanpa Nama. 2015. *MG996R High Torque Metal Gear Duall Ball Bearing Servo*.
http://www.electronicoscaldas.com/datasheet/MG996R_Tower-Pro.pdf. Diakses 26 Maret 2017 Pukul 21.00 WIB.
- [18] Tanpa Nama. 2014. *SG90 9g Micro Servo*.
<http://www.micropik.com/PDF/SG90Servo.pdf>. Diakses 26 Maret 2017 Pukul 20.00 WIB.
- [19] Muslimin. Santoso, Imam. Sofwan, Agus. 2010. *Monitoring Ruang Dengan Webcam Yang Dapat Diakses Melalui Handphone Menggunakan Jaringan Wi-Fi*
- [20] Anta, Alfian. 2015. *Lengan Robot Peniru Gerakan Tangan Manusia*. Yogyakarta. Universitas Sanata Dharma.
- [21] Naba, Agus. 2009. *Belajar Cepat Fuzzy Logic Menggunakan MATLAB*. Yogyakarta. ANDI Yogyakarta.
- [22] Mahargiyak, Eka. 2013. *Penerapan Logika Fuzzy Metode Sugeno untuk Sistem Pendukung Keputusan Prakiraan Cuaca*. Malang. Universitas Brawijaya.